Team Project:
A Surveillant Robot System

Status Report : 04/12/2005

Little Red Team

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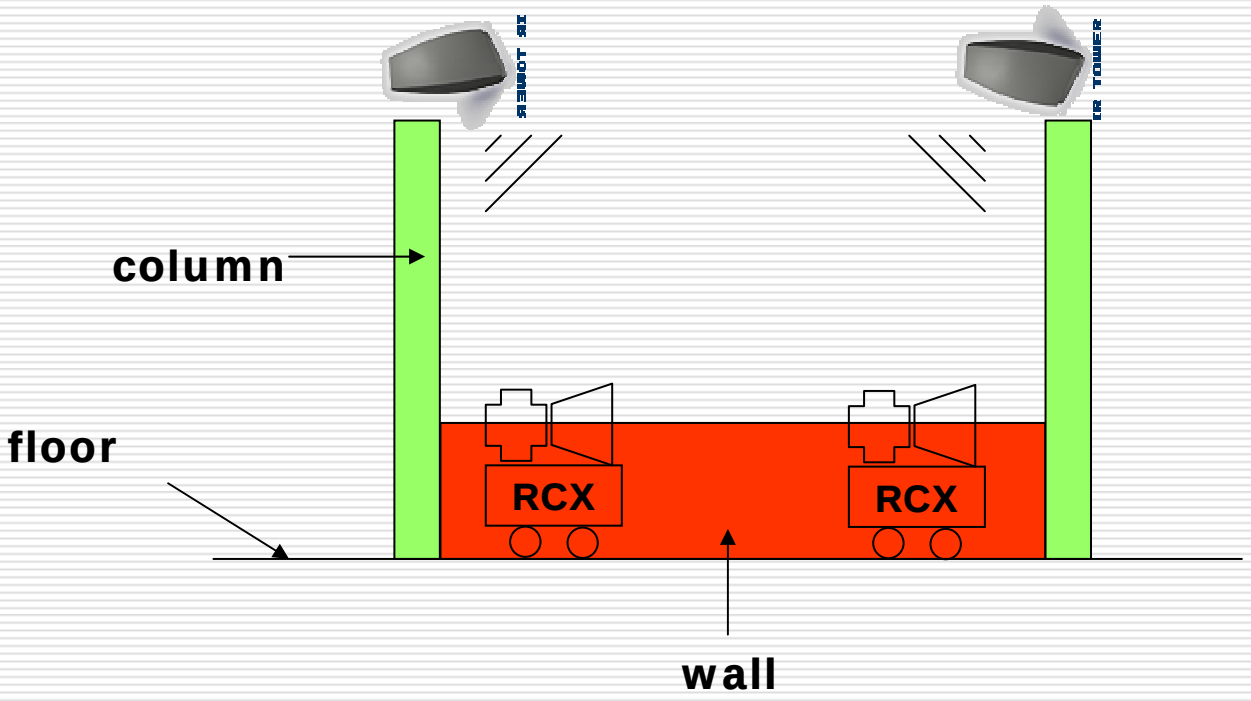
Agenda

- Team meeting & Problem
- Progress report

Team meeting

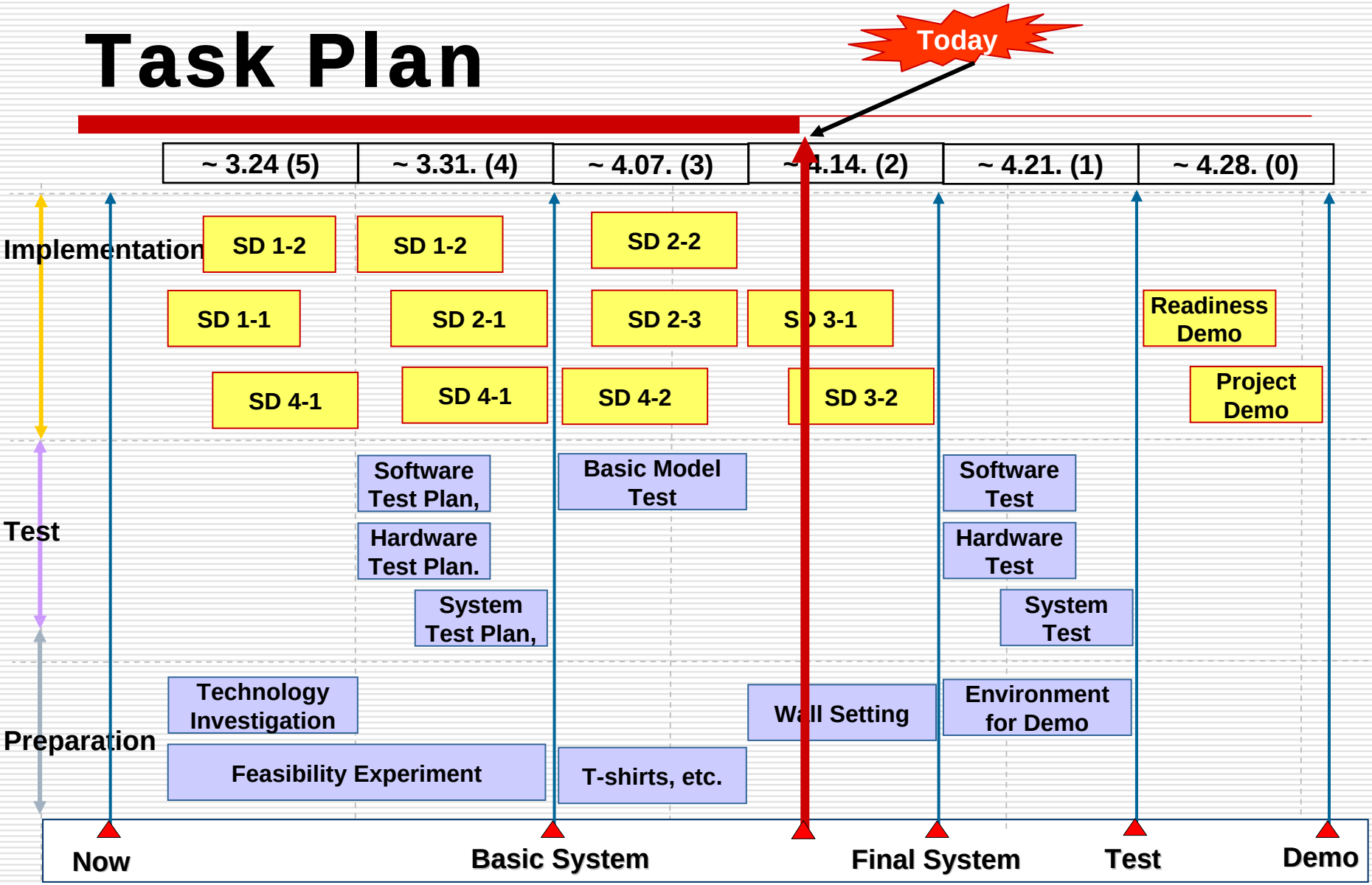
- We talked about IR tower.
- Each robot has each IR tower. If the main controller send a command to one robot only, however, two robot concurrently response the command. This is because IR signal and command does not ID to differentiate two main controller. Thus, we decide to include ID into signal.
  - Original objective of IR tower is to download program into RCX.
  - In our case, additional objective is to use signal as a tool to transmit command.
- Time goes by, physical problems is occurred rather than software problem.
- IR tower and IR signal is very sensitive to the direction. If a robot is positioned to opposite side of IR tower, robot can't receive the signal.

IR Tower Problem

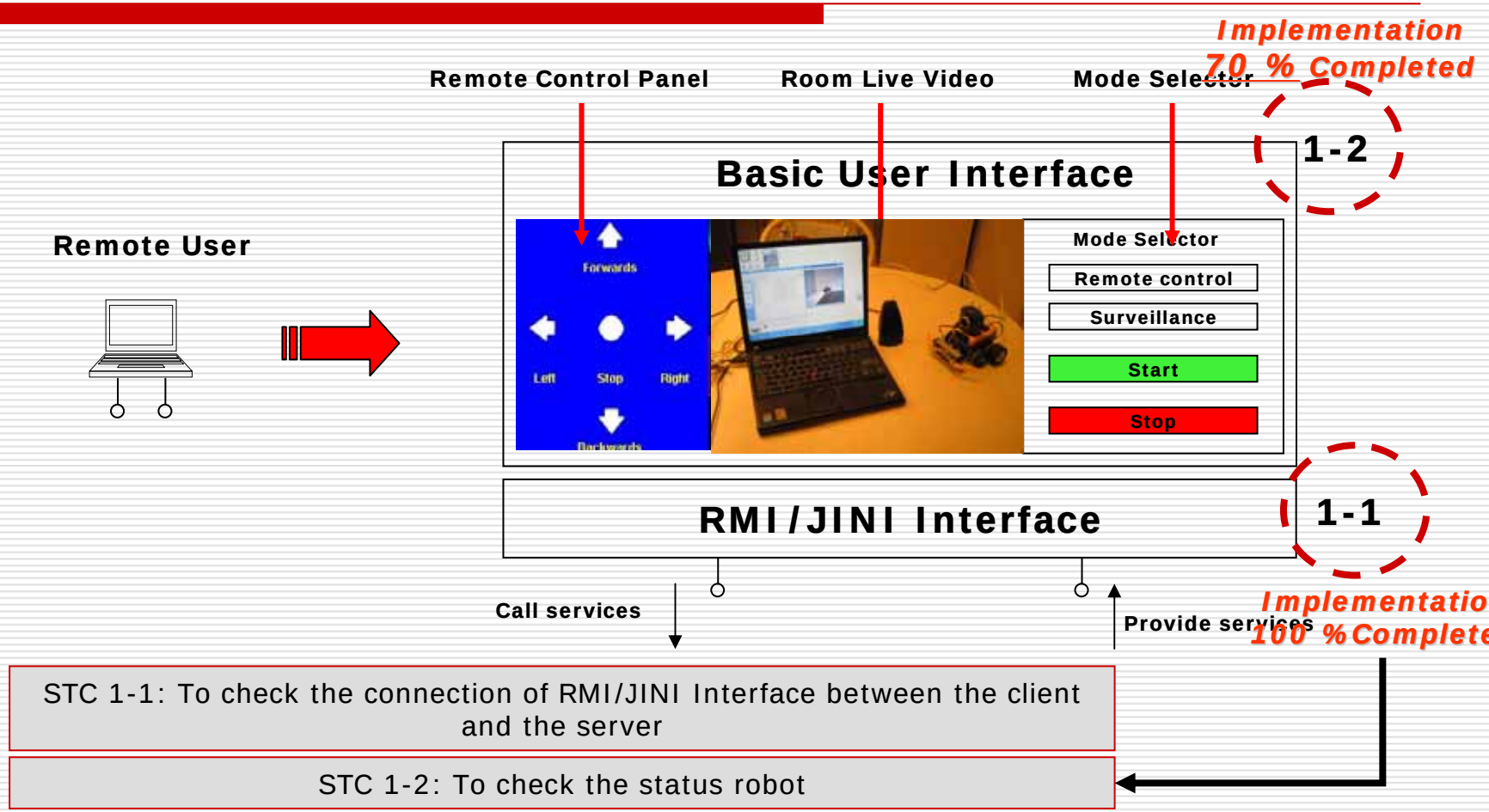


- The solution is to install two column or similar facility.
- RCX can increase the probability to receive signals from the IR

Task Plan


Today
~ 3.24 (5)
~ 3.31. (4)
~ 4.07. (3)
~ 4.14. (2)
~ 4.21. (1)
~ 4.28. (0)
Implementation
SD 1-2
SD 1-2
SD 2-2
SD 1-1
SD 2-1
SD 2-3
SD 3-1
Readiness Demo
SD 4-1
SD 4-1
SD 4-2
SD 3-2
Project Demo
Test
Software Test Plan,
Basic Model Test
Software Test
Hardware Test Plan.
Hardware Test
System Test Plan,
System Test
Preparation
Technology Investigation
Wall Setting
Environment for Demo
Feasibility Experiment
T-shirts, etc.
Now
Basic System
Final System
Test
Demo

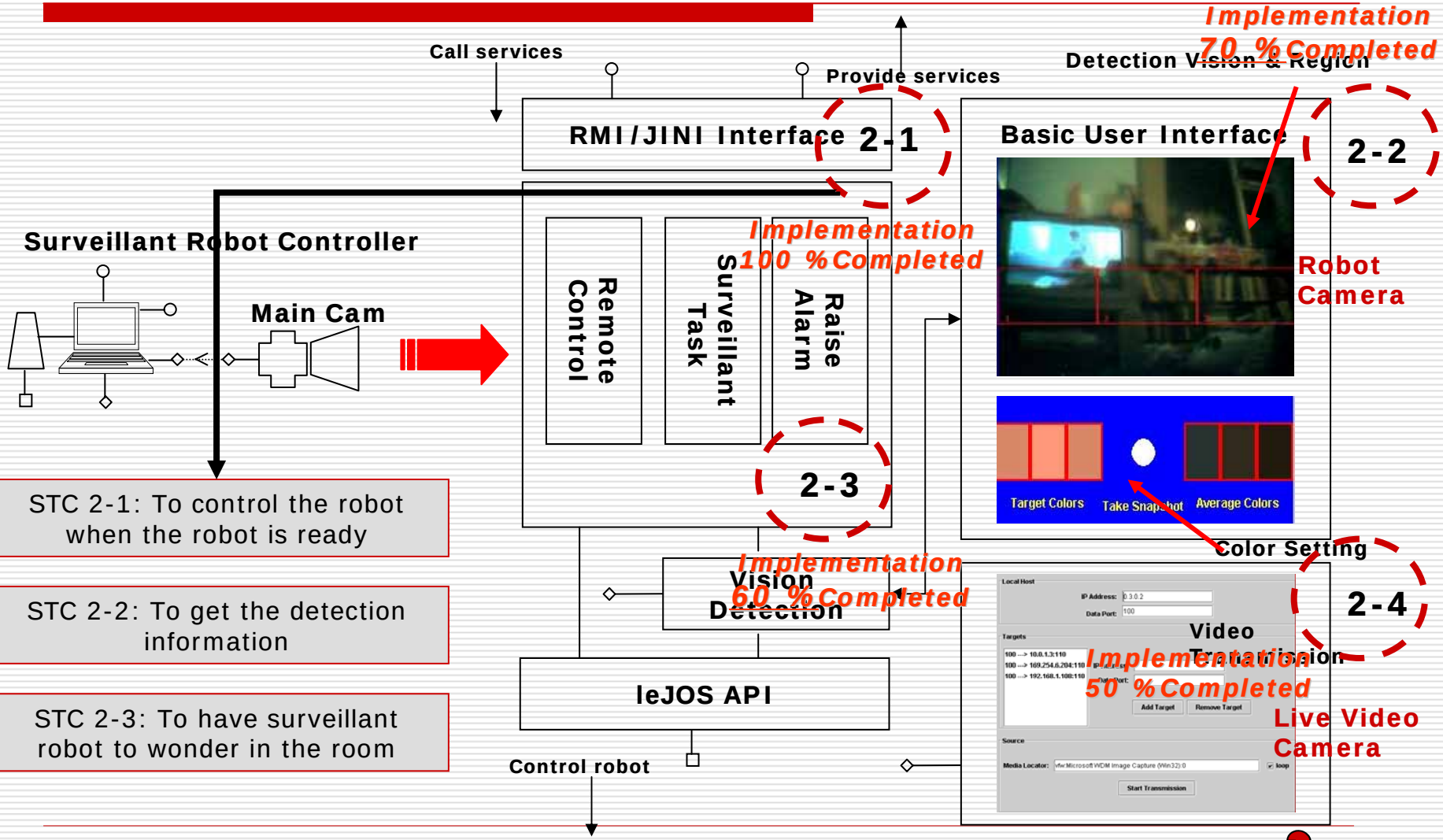
Software Design – SD#1



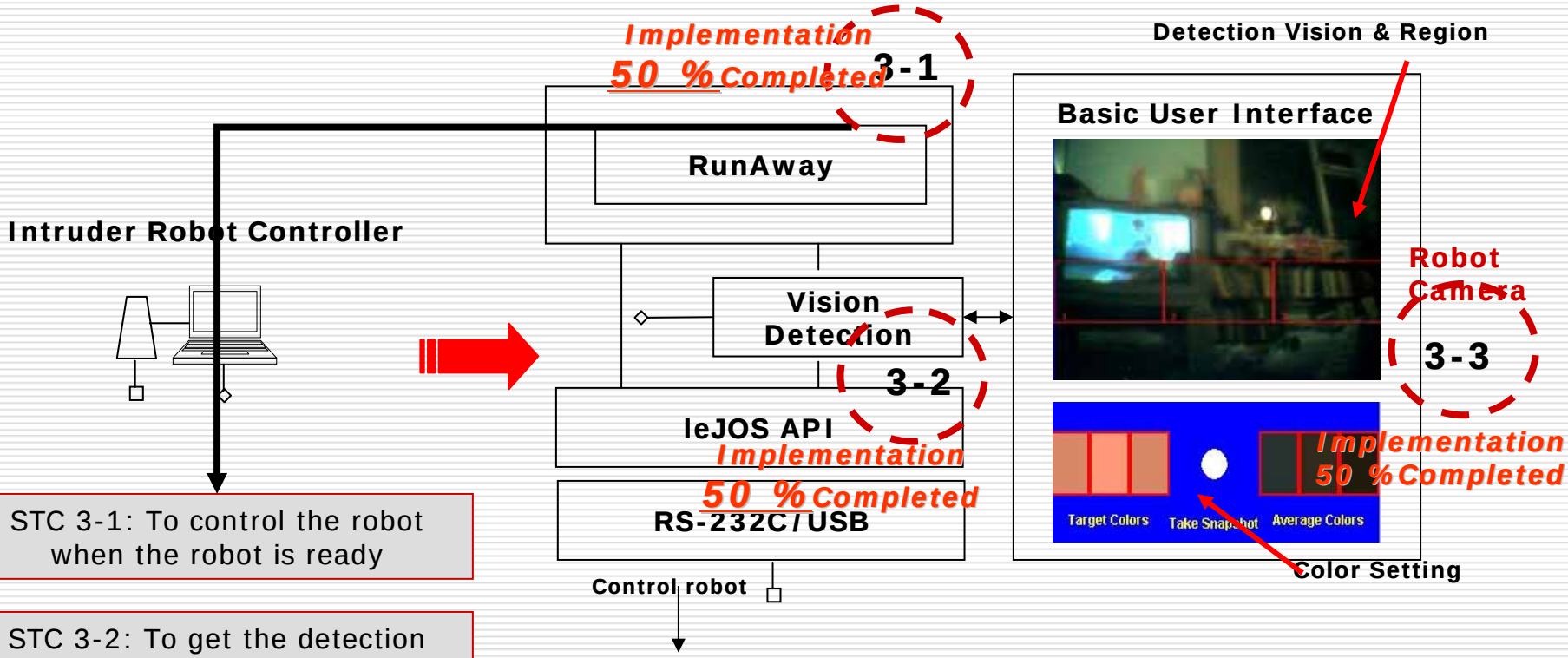
STC 1-1: To check the connection of RMI/JINI Interface between the client and the server

STC 1-2: To check the status robot

Software Design – SD#2



Software Design – SD#3



STC 3-1: To control the robot when the robot is ready

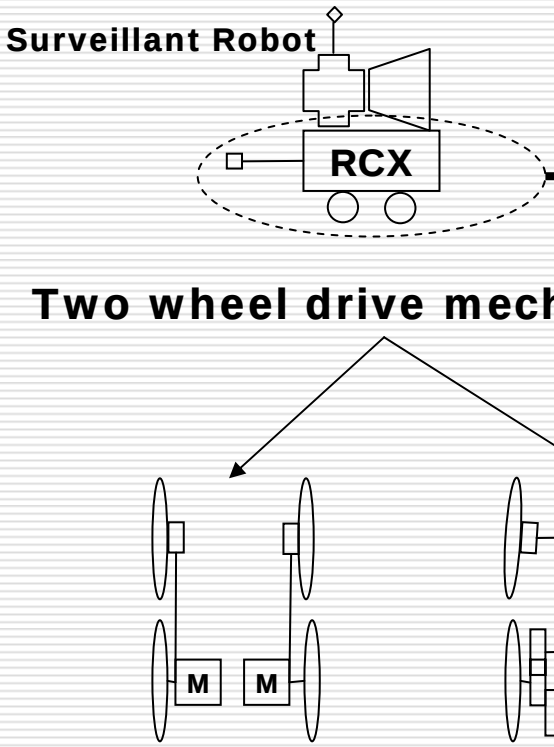
STC 3-2: To get the detection information

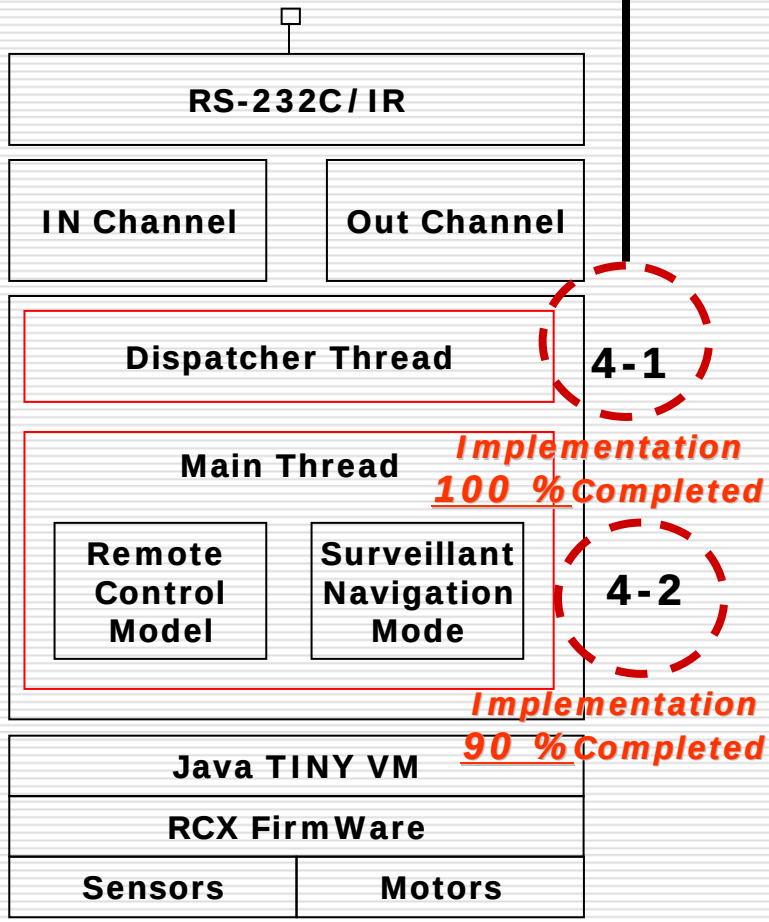
STC 3-3: To have surveillant robot to wonder in the room

Software Design – SD#4

STC4-1: To check dispatcher thread

STC4-2: To check main thread





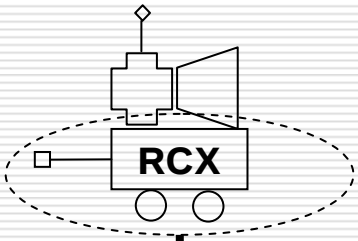
HTC1-1, HTC1-2 is testing

Software Design – SD#5

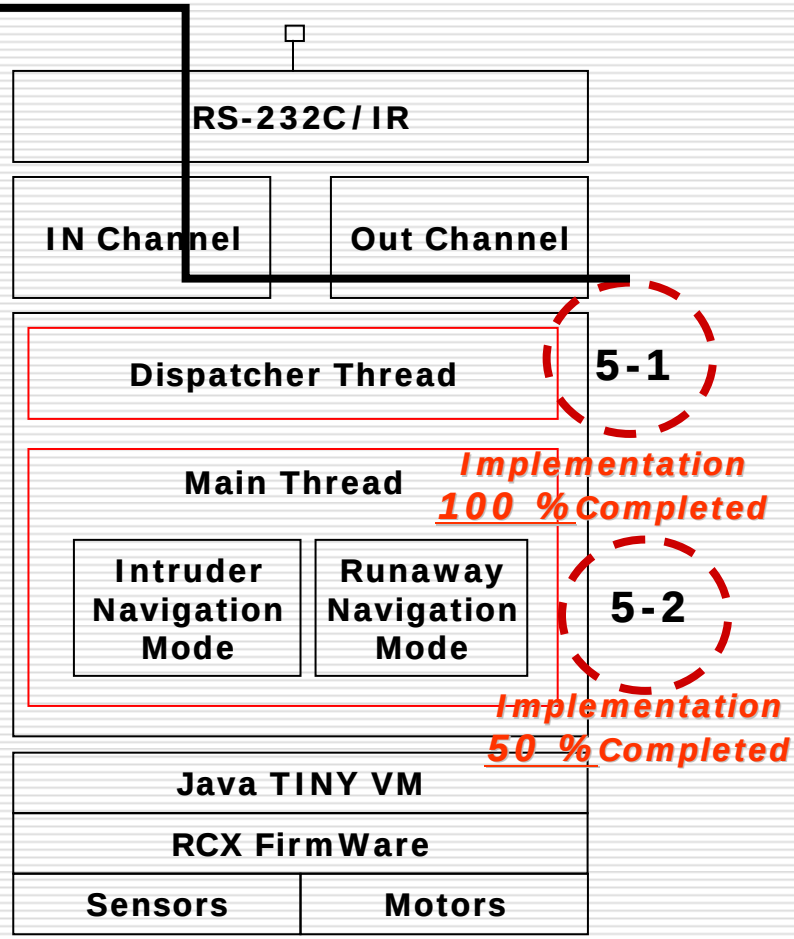
STC5-1: To check dispatcher thread

STC5-2: To check main thread

Intruder Robot



HTC2-1 is testing



Progress status

- Actual vs plan : 80% of the whole system is completed and tested.
- this week, we will start to integration test between all software and hardware.